

Statistical inference for spatio-temporal models

Variogram-based and Likelihood-based

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Why statistical inference of parametric models?

- ▶ characterize data generating process through a **small to moderate number of interpretable parameters**
- ▶ **predict** over space and time
- ▶ assess prediction **uncertainty**

Scope of this part of the tutorial

Key aspect will be **dependence of data over space (S) and time (T)**.
For implementation, focus on small number of R packages with powerful ST-specific features.

▶ stationary ST models

- ▶ Gaussian ST random field
- ▶ parametric
- ▶ non separability of S and T ?
separable $\Rightarrow Z(s_1, t_1)$ independent of $Z(s_2, t_2)$ conditional on $Z(s_1, t_2)$

▶ parameter inference

- ▶ least-squares-based, contrasting empirical and model ST variogram
- ▶ (composite) likelihood-based

Unfortunately, time is limited ...

- ▶ ~~non-gaussian dependence~~
- ▶ ~~hierarchical modeling~~
- ▶ ~~Bayesian approaches~~

Modeling framework : Spatio-temporal Gaussian models

Estimation

Hands on real data : space-time air pollution

Conclusion

Pretransformation to stationary Gaussian setup

In the following,

we will assume a **stationary Gaussian model** with **stationary mean** $\mu(s) \equiv \mu$.

- ▶ pre-transform margins to make data more “**Gaussian-like**” :
log-transform positive data, or Box–Cox transform for better symmetry around mean,...

Example : `boxcox` in MASS package

- ▶ use stationary model for **residuals** $\tilde{Z}(s, t)$ of a **regression model**, e.g.

$$Z(s, t) \sim \text{covariates}, \quad \tilde{Z}(s, t) = Z(s, t) - \hat{Z}(s, t)$$

1. fit regression with R functions such as `lm(...)`, `glm(...)`, `gam(...)`
2. extract fitted values $\hat{Z}(s, t)$
3. calculate residuals $\tilde{Z}(s, t)$ (+ make them more Gaussian-like)
4. fit stationary model to $\tilde{Z}(s, t)$

⇒ final model : combine

regression component (trend) + stationary component (dependence)

Spatio-temporal Gaussian model

Gaussian ST random field

$$Z(s, t) = \mu(s, t) + \sigma(s, t)Z^*(s, t), \quad s \in \mathbb{R}^2, t \geq 0$$

with

- ▶ **mean surface** $\mu(s, t)$, here $\mu(s, t) \equiv \mu$
- ▶ **variance surface** $\sigma^2(s, t)$, here $\sigma(s, t) \equiv \sigma > 0$
- ▶ standard Gaussian space-time field $Z^*(s, t)$
 - ▶ $\mathbb{E}Z^*(s, t) = 0, \mathbb{V}(Z^*(s, t)) = 1$
 - ▶ **space-time correlation function** $\text{Cor}((s_1, t_1), (s_2, t_2))$,
here $\text{Cor}(s, t)$ with $s = s_2 - s_1, t = t_2 - t_1$
↪ must be **nonnegative definite** :
 $\sum_{1 \leq i, j \leq d} a_i a_j \text{Cor}((s_i, t_i), (s_j, t_j)) \geq 0$ for any vector $\mathbf{a} = (a_1, \dots, a_d)^T$
 - ▶ model parameters govern dependence strength (S,T), measurement errors and nugget effects, anisotropy, nonseparability, ...

Observations and densities

- ▶ **observation** $\mathbf{z} = (z(s_1, t_1), \dots, z(s_d, t_d))^T$
- ▶ **typical ST scenario** : $d = \#\{\text{observation sites}\} \times \#\{\text{observation times}\}$
- ▶ d -variate Gaussian density of $\mathbf{z} \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$:

$$\varphi(\mathbf{z}; \boldsymbol{\mu}, \Sigma) = |\Sigma|^{-1/2} (2\pi)^{-d/2} \exp\left(-0.5(\mathbf{z} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{z} - \boldsymbol{\mu})\right),$$

with

- ▶ mean vector $\boldsymbol{\mu} = (\mu, \dots, \mu)^T$
- ▶ covariance matrix Σ based on **stationary ST covariance function** C :
 $\Sigma_{i_1, i_2} = C(s_{i_2} - s_{i_1}, t_{i_2} - t_{i_1}) = \sigma^2 \text{Cor}(s_{i_2} - s_{i_1}, t_{i_2} - t_{i_1})$

Parametric ST covariance models

Usually based on **combining standard stationary covariance models** :

$$C_S(s) = \sigma_S^2 \text{Cor}_S(s), \quad C_T(t) = \sigma_T^2 \text{Cor}_T(t)$$

exponential $\text{Cor}(x) = \exp(-\|x\|/\rho)$, powered exponential, Matérn, Cauchy, ...

- ▶ **separable** space-time models :

$$C_{ST}(s, t) = C_S(s) \times C_T(t) = \sigma_{ST}^2 \text{Cor}_S(s) \times \text{Cor}_T(t)$$

- ▶ **product-sum** (nonseparable) :

$$C_{ST}(s, t) = k C_S(s)C_T(t) + C_S(s) + C_T(t)$$

parameters σ_S , σ_T , k are identifiable and $\sigma_{ST}^2 = k\sigma_S^2\sigma_T^2 + \sigma_S^2 + \sigma_T^2$

- ▶ specific nonseparable ST model classes : Gneiting, Iaco-Cesare, Porcu, ...
- ▶ **nugget effects** in space and/or time :
 $\text{Cor}(x) = (1 - \text{nugget}/\sigma^2) \text{Cor}_0(x)$ for $\|x\| > 0$, with Cor_0 continuous in 0
- ▶ many types of **anisotropy** are possible

The Gneiting model [Gneiting, 2002]

$$C_{ST}(s, t) = \psi_T(t^2)^{-\delta/2} C_S \left(\|s\|^2 / \psi_T(t^2) \right)$$

- ▶ $\psi_T(t) = c + \gamma_T(t)$ with $c > 0$ and variogram $\gamma_T(\cdot)$
- ▶ $C_S(\cdot)$ covariance of Gaussian scale mixture type (Matérn, Cauchy, ...)
- ▶ parameter δ (\geq spatial dimension)

A flexible subclass (implemented in `CompRandFld`) :

$$C_{ST}(s, t) = \sigma^2 g_T(t)^{-1} \exp \left(-\frac{d_S(s)}{g_T(t)^{0.5\eta\kappa_S}} \right)$$

- ▶ $0 \leq \eta \leq 1$ **nonseparability parameter** (separable if $\eta = 0$)
- ▶ **power variograms** $d_T(t) = (|t|/\tau_T)^{\kappa_T}$ and $d_S(s) = (\|s\|/\tau_S)^{\kappa_S}$
- ▶ $g_T(t) = 1 + d_T(t)$ and $g_S(s) = 1 + d_S(s)$

R packages : How to create models ?

► RandomFields

- near endless range of available models (`?RMmodel`, `?RMmodelsSpacetime`)
- syntax may be somewhat technical owing to very large functionality
- example : Gneiting model with exponential C_S and power variogram ψ_T

```
#create model object:
model=RMnsst(phi=RMexp(scale=.5,var=1),psi=RMfbm(alpha=1),delta=3)
plot(model,dim=2) #visualize model (x=space, y=time)
#define coordinates: x,y, t (25 sites, observed at 100 time points)
xcoor=runif(25);ycoor=runif(25);tcoor=seq(from=0,to=10,by=.1)
#simulate one realization:
z=RFsimulate(x=xcoor,y=ycoor,T=tcoor,model=model,n=1)
length(z$variable1)
dim(z@coords)
head(z@coords)
tail(z@coords)
```

- product-sum model :

```
model=RMexp(proj="space",scale=5,var=2)*RMgauss(proj="time",scale=3)+
      RMmatern(proj="space",nu=1,scale=22)+
      RMexp(proj="time",scale=10,var=3)
```

- nugget effect : `RMnugget`

R packages : How to create models ?

- ▶ `CompRandFld`

- ▶ ST models are identified through character strings :

- ▶ for instance, "exp_cauchy" : separable model (S exponential, T Cauchy)
 - ▶ "gneiting", "iacocesare", "porcu", ...
 - ▶ `?Covmatrix` for a description of implemented models

- ▶ internal parameter names : `CorrelationParam("gneiting")`

- ▶ simulation (interface to `RandomFields`) :

```
z=RFsim(xcoor,ycoor,tcoor,corrmodel="exp_exp",  
        param=list(nugget=0,mean=0,scale_s=0.3,scale_t=0.5,sill=1))$data  
dim(z) # 100 x 25 here
```

R packages : How to create models ?

► gstat

- models are R objects (but no simulation facility)
- `vgm()` to get list of available standard models
- available constructions : product-sum, metric, sum-metric...
but no specific ST classes

► separable model

```
> sepmod=vgmST("separable", space=vgm(psill=0.9,"Exp", range=147,nugget=0.1),
+             time =vgm(psill=0.9,"Exp", range=3.5,nugget=0.1),sill=40)
> extractParNames(sepmod)
[1] "range.s" "nugget.s" "range.t" "nugget.t" "sill"
```

► product-sum model

```
> vgmST("productSum",space=vgm(0.9,"Exp",1,1), time=vgm(0.9,"Gau",1,1),k=1)
```

Modeling framework : Spatio-temporal Gaussian models

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Conclusion

Covariance function C and semi-variogram γ

Variograms are more general than covariance functions since they allow handling intrinsically stationary processes (with stationary increments).

We assume **stationary**, leading to **equivalent representation** in terms of the variogram or the covariance function.

Semi-variogram of stationary ST field :

$$\gamma(s, t) \stackrel{\text{def}}{=} 0.5\mathbb{E} (Z(s, t) - Z(0, 0))^2 = \sigma^2 - C(s, t)$$

where $\sigma^2 = C(0, 0)$.

Typical parameters

Assumption : ST process is stationary

Parameters are either to estimate or to be fixed a priori.

- ▶ mean μ
- ▶ variance σ_{ST}^2
- ▶ ST nugget or measurement errors : $\theta_{\text{nugget}} = \sigma_{ST}^2 - \lim_{t \rightarrow 0, \|s\| \rightarrow 0} C(s, t)$
- ▶ spatial geometric anisotropy $\Delta s \rightsquigarrow \begin{pmatrix} b & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \cos(a) & -\sin(a) \\ \sin(a) & \cos(a) \end{pmatrix} \Delta s$
 - ▶ rotation $a \in [0, \pi)$
 - ▶ dilation $b > 0$
- ▶ correlation function : scale and shape parameters

Here : empirical estimation of μ and σ_{ST}^2 :

- ▶ $\hat{\mu} = \frac{1}{d} \sum_{(s_i, t_i)} z(s, t)$, where $d = \#\{(s_i, t_i)\}$ (mean function of \mathbb{R})
- ▶ $\hat{\sigma}_{ST}^2 = \frac{1}{d} \sum_{(s_i, t_i)} (z(s, t) - \hat{\mu})^2$ (var function of \mathbb{R})

Estimating covariance parameters : variogram-based or likelihood-based

► **variogram-based :**

- **requires empirical ST variogram**
- **weighted least squares (WLS)** between empirical and parametric model variogram

► **likelihood-based**

- **maximum likelihood (ML)** : estimate parameter vector θ

$$\hat{\theta}_{ML} = \arg \max_{\theta} \ell(\theta; z)$$

with likelihood $\theta \mapsto \ell(\theta; z) = \varphi(z; \mu_{\theta}, \Sigma_{\theta})$

- **tapering** [Furrer et al., 2006, Kaufman et al., 2008, Stein, 2013]
for reducing computational cost
 - use $\tilde{C}(s, t) = C(s, t) \times C_0(s, t)$ with C_0 compactly supported (Wendland, ...) \rightsquigarrow "sparse" Σ
 - performance may be disappointing in practice
- **maximum composite likelihood, e.g. pairwise likelihood (PL)**

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Weighted least squares between empirical and model variogram

Define set of **distance classes**

$$D_k = \{(s_i, t_i) : \text{dist}((s_i, t_i), (\tilde{s}_k, \tilde{t}_k)) \leq \varepsilon_k\}, \quad k = 1, \dots, K$$

(typically a space-time grid of class barycenters)

WLS estimator :

$$\hat{\theta}_{WLS} = \arg \min_{\theta} \sum_{k=1}^K \omega_k |\gamma_{\theta,k} - \hat{\gamma}_k|^2$$

- ▶ $\omega_k = 1$ ordinary least squares
- ▶ $\omega_k = |D_k|/\gamma_{\hat{\theta},k}^2$: correct for variance of $\hat{\gamma}_k$
- ▶ overweight small ST distances, ... (similar to tapering, weighted PL)

Maximum composite likelihood

[Lindsay, 1988, Varin et al., 2011]

Pairwise likelihood if based on bivariate distributions :

$$\text{PL}(\boldsymbol{\theta}; \mathbf{z}) = \prod_{i_1, i_2} f_{\boldsymbol{\theta}, i_1, i_2}(z_{i_1}, z_{i_2})$$

maximum pairwise likelihood : $\boldsymbol{\theta}^* = \arg \max_{\boldsymbol{\theta} \in \Theta} \text{PL}(\boldsymbol{\theta}; \mathbf{z})$

- ▶ $f_{\boldsymbol{\theta}, i_1, i_2} \in \text{density of } (Z(s_1, t_1), Z(s_2, t_2))^T, Z(s_1, t_1) - Z(s_2, t_2) \text{ or } Z(s_1, t_1) \mid Z(s_2, t_2)$
- ▶ **good asymptotic properties** : consistency, normality, unbiasedness
⇒ calculation of standard errors, hypothesis testing ...
- ▶ reduce computational burden by **using only pairs that are "close" in space and time**, which may further reduce bias in certain cases

Model selection

Often, we have to **choose between several (fitted) covariance models**.

Techniques :

- ▶ visual comparison "**fitted vs. empirical**" for covariance function
- ▶ **cross-validation**
- ▶ **information criteria such as CLIC** (Composite Likelihood Information Criterion)
- ▶ nested models : likelihood-based **statistical hypothesis tests** (with adaptations to composite likelihood)

Selected R packages at a glance

	RandomFields	CompRandFld	gstat
Strengths	models, simulation	statistical inference	data structures, exploration
spacetime R objects	–	–	yes
simulation	RFsimulate	RFsim	(predict.gstat)
Σ_θ	RFcovmatrix	Covmatrix	(variogramLine)
emp. ST variogram	RFempiricalvariogram	EVariogram	variogramST
ML	RFfit(?)	FitComposite	–
PL	–	FitComposite	–
WLS	RFfit(?)	WLeastSquare	fit.StVariogram
standard errors	RFfit(?)	FitComposite	–
information criteria	AIC	AIC, CLIC	–
CV	RFcrossvalidate	–	krige.cv
kriging	RFinterpolate	Kri	krigeST
test nested models	–	HypoTest	–
separable	yes	yes	yes
product-sum, ...	(yes)	–	yes
Gneiting	RMnsst	yes	–
spatial anisotropy	yes	–	(partial)
tapering	–	yes	–

Other packages with less general functionality or different approaches :
 rgeos (spatial), SpatioTemporal ...

⚠ weak interpackage compatibility (data structures, models)
 except for spacetime/gstat

Modeling framework : Spatio-temporal Gaussian models

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Conclusion

Data structure

- ▶ **AirBase daily observation data** (PM10, O3, ...) on **irregularly spaced observation sites**
 - ▶ Europe, with ≈ 400 stations in France
 - ▶ ⚠ many missing data
 - ▶ station types : "background", "traffic", "industry", ...
- ▶ **daily predictions of chemical-physical CHIMERE model** (forecasts and hindcasts) over regular grid
- ▶ no other covariates (weather, urbanisation, industries, ...), but already partially integrated into the CHIMERE values

To avoid handling strong nonstationarities, we **keep only background stations**.

Modeling approach : PM10

We focus on modeling the **particulate matter concentrations** PM10.

ST Gaussian model for error correction for

$$\text{observation}(s, t) - \text{prediction CHIMERE}(s, t)$$

- ▶ space-time variation of mean surface is modeled through the CHIMERE values
- ▶ ⚠ different spatial supports require interpolating CHIMERE values to irregular observation sites \Rightarrow use bilinear spatial interpolation (`interp.surface-function` from `fields` package)

Load and select data (1/2)

- ▶ load previously created data objects : daily observations, CHM predictions, stations
- ▶ select French background stations

```
> load(paste0(DATA, 'OBS_jour.Rdata'))  
> load(paste0(DATA, 'CHM.Rdata'))  
> load(paste0(DATA, 'stations.Rdata'))  
> IDs_bg    <- stations$station_european_code[stations$type_of_station=="Background"]  
> IDs_fr    <- stations$station_european_code[stations$country_name=="France"]  
> IDs_bgfr  <- intersect(IDs_bg,IDs_fr)  
> idx_stations <- which(stations$station_european_code %in% IDs_bgfr)  
> coord     <- cbind(stations$station_longitude_deg,stations$station_latitude_deg)[idx_stations]  
> dim(coord) #around 700 French background stations  
[1] 705  2
```

Load and select data (2/2)

- ▶ choose 3-month period (Jan-Mar 2014) for fitting models
- ▶ transform from latitude-longitude to Lambert93 projection

(using STFDF object OBS_sel)

```
> tstart    <- "2014-01-01"
> tend      <- "2014-03-31"
> OBS_jour  <- OBS_jour[OBS_jour$ID %in% IDs_bgfr,]
> OBS_sel   <- stConstruct(OBS_jour,space=c('long','lat'),time='date',
+                           SpatialObj=SpatialPoints(OBS_jour[,c('long','lat')]))
> OBS_sel   <- as(OBS_sel,"STFDF")
> proj4string(OBS_sel)="+init=epsg:4326"
> OBS_sel   <- OBS_sel[,paste0(tstart,"::",tend)]
> OBS_sel@sp <- spTransform(OBS_sel@sp, CRS("+init=epsg:2154"))
```

Interpolate CHIMERE predictions

- ▶ interpolate from prediction grid to observation sites through simple bilinear interpolation : CHM_sites
- ▶ save residuals $PM10_{res} = (PM10 - CHM_sites)$ into OBS_sel

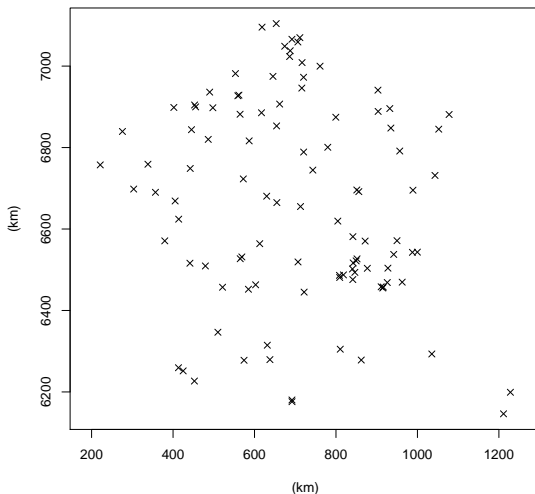
```
> library(fields)
> CHM_sel <- CHM[as.character(CHM$time)>=tstart&as.character(CHM$time)<=tend,]
> grid_CHM <- unique(cbind(CHM_sel$lon,CHM_sel$lat))
> CHM_mat <- matrix(CHM_sel$PM10, nrow=nrow(grid_CHM))
> dim(CHM_mat)
[1] 11211    90
> lon_grid <- sort(unique(CHM_sel$lon))
> lat_grid <- sort(unique(CHM_sel$lat))
> idx_sites_obs <- match(unique(OBS_sel@data$ID),IDs_bgfr)
> fun2interp <- function(i){
+   tmp <- list(x=lon_grid,y=lat_grid,
+               z=matrix(CHM_mat[,i],length(lon_grid),length(lat_grid)))
+   interp.surface(tmp, coord[idx_sites_obs,])
+ }
> CHM_sites <- sapply(1:ncol(CHM_mat),fun2interp)
> OBS_sel@data$CHM <- as.numeric(CHM_sites)
> OBS_sel@data$PM10res <- OBS_sel@data$PM10-as.numeric(CHM_sites)
```

Estimation with CompRandFld – Remove missing data

- ▶ need observation matrix (time \times sites) **without missing values** CHM_sites

```
> data_mat <- matrix(OBS_sel@data$PM10res,ncol=dim(OBS_sel)[1],nrow=dim(OBS_sel)[2],byrow=
> dim(data_mat)
[1] 90 378
> mean(is.na(data_mat)) #around 44 per cent of missing data
[1] 0.4398001
> data2keep=list(data_mat=data_mat,times=1:nrow(data_mat),stations=1:ncol(data_mat))
> cleandata=function(data2keep,propNA){
+   idx2keep=apply(is.na(data2keep$data_mat),1,mean) < propNA
+   data2keep$times=data2keep$times[idx2keep]
+   data2keep$data_mat <- data2keep$data_mat[idx2keep,]
+   idx2keep=apply(is.na(data2keep$data_mat), 2, mean) < propNA
+   data2keep$stations=data2keep$stations[idx2keep]
+   data2keep$data_mat <- data2keep$data_mat[,idx2keep]
+   data2keep
+ }
> data2keep=cleandata(data2keep,.9)
> data2keep=cleandata(data2keep,.2)
> data2keep=cleandata(data2keep,.1)
> data2keep=cleandata(data2keep,.05)
> data2keep=cleandata(data2keep,.025)
> data2keep=cleandata(data2keep,.01)
> data2keep=cleandata(data2keep,.10^{-10})
> data_mat=data2keep$data_mat
> dim(data_mat) #we keep 70 stations and 103 days
[1] 70 103
```

Estimation with CompRandFld – Selected sites



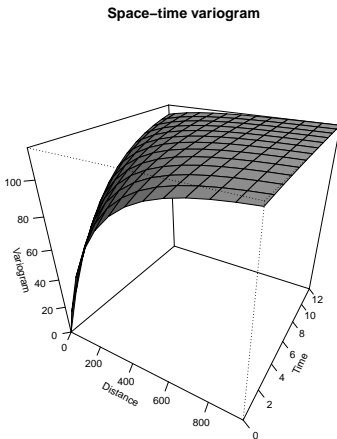
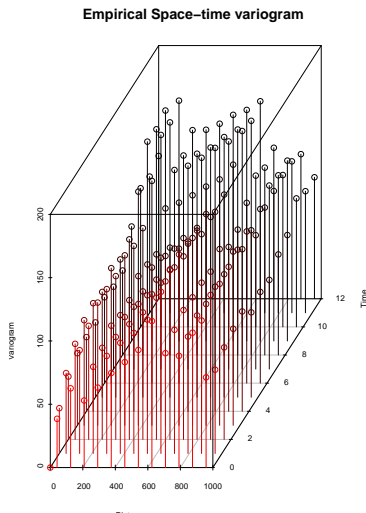
Estimation with CompRandFld – Define covariance models

```
> mean_est <- mean(data_mat); mean_est
[1] 8.024326
> var_est <- var(as.numeric(data_mat)); var_est
[1] 116.0013
> cormod1 <- "exp_exp"
> fixed1 <- list(mean=mean_est,nugget=0,sill=var_est)
> start1 <- list(scale_s=200,scale_t=2)
> cormod2 <- "exp_exp"
> fixed2 <- list(mean=mean_est,sill=var_est)
> start2 <- list(scale_s=200,scale_t=2,nugget=0)
> cormod3 <- "gneiting"
> fixed3 <- list(sill=var_est,mean=mean_est,nugget=0,power_s=1,power_t=1)
> start3 <- list(scale_s=200,scale_t=2,sep=.5)
> cormod4 <- "gneiting"
> fixed4 <- list(sill=var_est,mean=mean_est,power_s=1,power_t=1)
> start4 <- list(scale_s=200,scale_t=2,sep=.5)
> cormod5 <- "gneiting"
> fixed5 <- list(sill=var_est,mean=mean_est,nugget=0,power_s=.5,power_t=.5)
> start5 <- list(scale_s=200,scale_t=2,sep=.5)
> cormod6 <- "gneiting"
> fixed6 <- list(sill=var_est,mean=mean_est,power_s=.5,power_t=.5)
> start6 <- list(scale_s=200,scale_t=2,sep=.5)
> cormod7 <- "gneiting"
> fixed7 <- list(sill=var_est,mean=mean_est,nugget=0)
> cormod8 <- "gneiting"
> fixed8 <- list(sill=var_est,mean=mean_est)
```

Estimation with CompRandFld – Estimate Model 1 (PL / WLS)

```
> fit1PL <- FitComposite(data=data_mat,coordx=coord_fit,coordt=times_fit,maxdist=300,
  maxtime=4,corrmodel=cormod1,likelihood="Marginal",type="Pairwise",fixed=fixed1,
  start=start1,varest=T)
> fit1PL
[...] Maximum log-Composite-Likelihood value: -6577607.64
CLIC : 13155436
Estimated parameters:
scale_s  scale_t
238.015   4.141
Standard errors:
scale_s  scale_t
5.8847   0.1825
Variance-covariance matrix of the estimates:
scale_s      scale_t
scale_s  34.630069   0.007295
scale_t   0.007295   0.033290
> library(scatterplot3d)
> Covariogram(fit1PL,vario=vgm_emp,show.vario=T,pch=20)
> fit1WLS <- WLeastSquare(data=data_mat,coordx=coord_fit,coordt=times_fit,maxdist=300,maxt.
> fit1WLS
[...] Estimated parameters:
scale_s  scale_t
306.903   3.131
> (fit1PL$param-fit1WLS$param)/pmax(abs(fit1PL$param),abs(fit1WLS$param))
scale_s      scale_t
-0.2244608   0.2439148
```

Estimation with CompRandFld – Plot empirical vs. fitted



Estimation with CompRandFld – Fit and compare all models

- ▶ select model with minimal composite likelihood information criterion (CLIC)
- ▶ test for nested models

```
> load(file=paste0(DATA,"fitsWLS.Rdata"))
> load(file=paste0(DATA,"fitsPL.Rdata"))
> which.min(unlist(sapply(fitsPL,getElement,"clik"))))
[1] 8
> unlist(sapply(fitsPL,getElement,"clik"))
[1] 13155436 13129950 13149224 13130463 13138167 13126159 13137701 13126002
> fit8 <- fitsPL[[8]]
> fit7 <- fitsPL[[7]]
> fit5 <- fitsPL[[5]]
> HypoTest(fit8,fit7,fit5,statistic="Wald")
Num.Par Diff.Par Df      Chisq Pr(>chisq)
fit8      6      NA NA      NA      NA
fit7      5       1  1 0.9344535 0.33370837
fit5      3       2  2 8.7120541 0.01282926
```

Previous model selection criteria lead us to keep one of Models 7 or 8 :

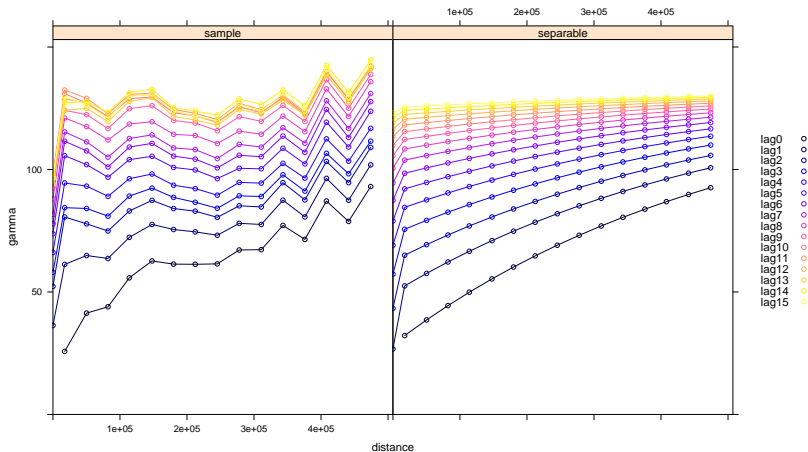
```
> fit7$param
power_s    power_t    scale_s    scale_t      sep
0.4371113  0.7314831 424.7527140  3.6254877  1.0000000
> fit8$param
nugget    power_s    power_t    scale_s    scale_t      sep
8.3616423  0.4290766  0.7774891 632.4262168  4.3469095 1.0000000
```

Estimation with gstat – WLS fitting

- ▶ direct use of spacetime data structures
- ▶ Weighted Least Squares fitting for a selection of models (separable, product-sum, metric, sum-metric ...)
- ▶ ⚠ time unit is 1 hour, space unit is 1m

```
> vario <- variogramST(PM10res~1,data=OBS_sel)
|=====| 100%
Warning message:
In variogramST(PM10res ~ 1, data = OBS_sel) :
strictly irregular time steps were assumed to be regular
> separableModel <- vgmST("separable",space=vgm(psill=0.9,"Exp",range=500000,nugget=0.1),
+                        time=vgm(psill=0.9,"Exp",range=3*24,nugget=0.1),sill=200)
> extractParNames(separableModel)
[1] "range.s" "nugget.s" "range.t" "nugget.t" "sill"
> separable_fit <- fit.StVariogram(model=separableModel,object=vario)
> plot(vario,separable_fit,all=T,map=F)
```

Estimation with gstat – Plot empirical vs. fitted

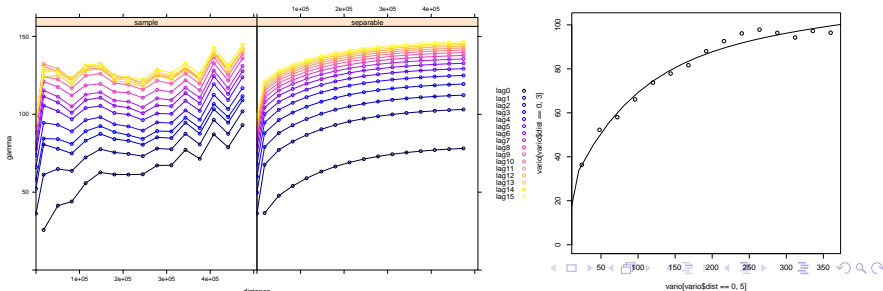


Fit does not seem to be very accurate.

Estimation with gstat – Manual "eye fit"

- ▶ convergence of parameter optimization seems questionable ...
- ▶ need to play around with initial parameters
- ▶ instead, can try manual "eye fit" :
visual inspection for various parameter configurations to get good match

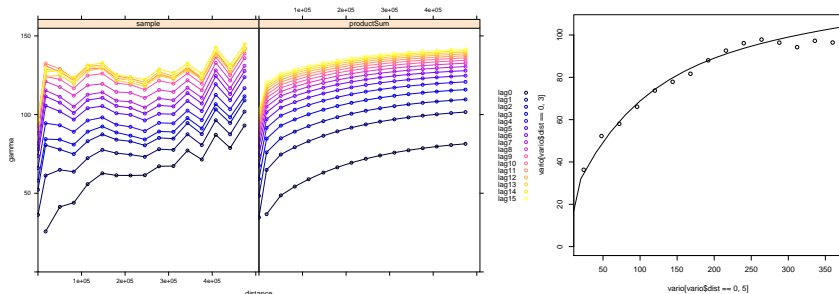
```
sill <- 250  
separable_man <- vgmST("separable",space=vgm(.18,"Exp",1.5e5,0.01,  
add.to=vgm(.12,"Exp",8e3,.01)),time=vgm(80/sill,"Exp",1670,19/sill,  
add.to=vgm(66/sill,"Exp",85,0)),sill=sill)  
plot(vario,separable_man,all=T,map=F)  
variot(ProductSum_fit,vario)
```



Estimation with gstat – Various other fits

- convergence seems to strongly depend on very good initial values
- well-chosen manual "eye fits" seem to provide better results (?)

```
> ProductSum_man <- vgmST("productSum",space=vgm(12.5,"Exp",2e5,0,add.to=vgm(10,"Exp",9e3,0,  
+ time=vgm(35,"Exp",800,9.5,add.to=vgm(36,"Exp",85,0)),k=0.035)  
> plot(vario,ProductSum_man,all=T,map=F)  
> variot(ProductSum_man,vario)
```



Modeling framework : Spatio-temporal Gaussian models

Estimation

Hands on real data : space-time air pollution

Conclusion

Some take-home messages

- ▶ getting the ST dependence right is paramount to **predicting values and uncertainty over space and time**
- ▶ an ever-increasing functionality for estimating ST models is available in R
- ▶ interesting future extensions of packages?
(NA data in `CompRandFld`, ST estimation facilities in `RandomFields`, ...)
- ▶ currently, `CompRandFld` most complete package with respect to ST estimation
- ▶ complex ST models make parameter estimation challenging
 - ⇒ model selection tools use approximations, may sometimes mislead
 - ⇒ always **check if model fit looks "trustworthy"**
 - ⇒ compare estimation for different initial values
- ▶ there are many ways to **extend an S model to include T dependence**, **there may be several good choices**



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